



Slot: B2

SCHOOL OF COMPUTER SCIENCE AND ENGINEERING (SCOPE)

CAT-II Examination Winter Semester 2024-2025

Programme and Branch: B.Tech – CSE

Course Code: BCSE311L

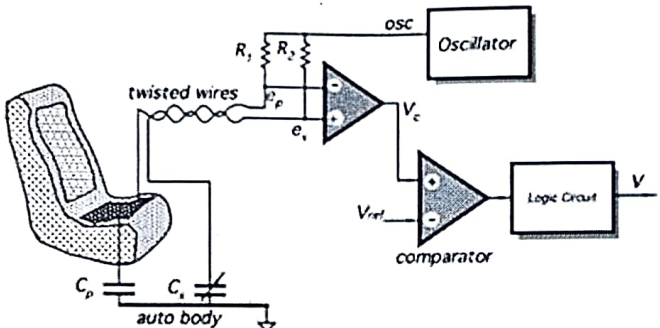
Course Title: Sensors and Actuator Devices

Duration: 90 minutes

Class Numbers: 1972/ 1976

Total Marks: 50

S. No	Answer All Questions	Marks	CO	BL																				
1	A vaccine research laboratory is developing a high-sensitive optical detection system for low-light imaging applications using photomultiplier tubes (PMTs). The device operates on the principle of the photoelectric effect and enhances detection by increasing the number of released electrons. During testing, the following specifications were used: ✓ A UV light source with a wavelength of $\lambda = 250$ nm was used to illuminate the photocathode, which has a work function of 2.5 eV. ✓ The photomultiplier tube consists of five dynodes, each with an electron multiplication factor of $n_1 = 4$. ➤ Calculate the energy of the incident UV photons and determine whether the given light source is capable of ejecting electrons from the photocathode. ➤ Evaluate and validate the significance of the statement “<i>The final output current was observed to be ten times higher than the initial photoelectron count</i>”	10	CO2	3																				
2	Elucidate why a passive IR sensor is not an optimal solution for pedestrian detection. A self-driving car uses Active Infrared (AFIR) sensors for pedestrian detection in low-visibility conditions. On a foggy winter night, the system fails to detect a pedestrian, triggering a safety issue. Various parameters in the following table depict the given scenario:- <table><tr><th>Parameter</th><th>Value</th></tr><tr><td>AFIR Sensor Wavelength, λ</td><td>950 nm</td></tr><tr><td>Transmitter Power, P_t</td><td>100 mW (0.1 W)</td></tr><tr><td>Path Distance, d</td><td>30 m (round trip)</td></tr><tr><td>Detection Threshold, P_{thresh}</td><td>10 mW</td></tr><tr><td>Fog Attenuation, α</td><td>3 dB/m</td></tr><tr><td>Streetlight IR Noise</td><td>20 mW</td></tr><tr><td>Polarization Filter Effectiveness</td><td>90% noise reduction</td></tr><tr><td>Long Wave IR (Alternative Wavelength), λ'</td><td>10 μm</td></tr><tr><td>Long Wave IR Attenuation, α'</td><td>0.1 dB/m</td></tr></table> As per the scenario described, answer the following questions:- ➤ Analyze why the AFIR sensor failed to detect the pedestrian in foggy conditions and justify your answers ➤ Compute the received power at the detector after 30m travel under foggy condition. ➤ Assess the impact of streetlight IR interference on pedestrian detection by computing the pre-filtered and post-filtered Signal-to-Noise Ratio (SNR). ➤ Verify the improvement in received power if the system shifts from 950 nm to 10 μm (Long wave IR) in the same conditions. ➤ Propose an optimized sensor layout to improve the detection accuracy while minimizing additional power consumption with sufficient justifications	Parameter	Value	AFIR Sensor Wavelength, λ	950 nm	Transmitter Power, P_t	100 mW (0.1 W)	Path Distance, d	30 m (round trip)	Detection Threshold, P_{thresh}	10 mW	Fog Attenuation, α	3 dB/m	Streetlight IR Noise	20 mW	Polarization Filter Effectiveness	90% noise reduction	Long Wave IR (Alternative Wavelength), λ'	10 μm	Long Wave IR Attenuation, α'	0.1 dB/m	15	CO2	3
Parameter	Value																							
AFIR Sensor Wavelength, λ	950 nm																							
Transmitter Power, P_t	100 mW (0.1 W)																							
Path Distance, d	30 m (round trip)																							
Detection Threshold, P_{thresh}	10 mW																							
Fog Attenuation, α	3 dB/m																							
Streetlight IR Noise	20 mW																							
Polarization Filter Effectiveness	90% noise reduction																							
Long Wave IR (Alternative Wavelength), λ'	10 μm																							
Long Wave IR Attenuation, α'	0.1 dB/m																							

3	Investigate the operation of a magnetometer using the following parameters:- ✓ Principles of operation ✓ Output voltage ✓ Sensitivity	10	CO3	2
4	An automotive company is developing a capacitive seat occupancy detection system for vehicles, as illustrated in the given diagram:-  In this system, a metal plate under the seat cushion, acts as one plate of a capacitor, while the vehicle body serves as the ground. When the seat is unoccupied, the baseline capacitance (C_p) is 50 pF. However, when a person enters the vehicle, their body introduces additional capacitances: ✓ Capacitance between the seat plate and the body (C_a) = 100 pF ✓ Capacitance between the body and the vehicle ground (C_b) = 150 pF With respect to the given scenario, provide answers to the following questions:- ➤ Calculate the total capacitance (C) of the system when an occupant is present. ➤ Analyze how the oscillator and comparator circuit in the diagram detects changes in capacitance and determines occupancy. ➤ Find out if the system can accurately detect a person's presence when the detection threshold is set at 100 pF by performing the necessary calculations. ➤ Suggest a modification to improve the sensitivity of the capacitive detection system for automotive applications. ➤ Discover any two applications for this capacitive seat occupancy detection system and analyze how it can be integrated with emerging vehicle technologies, such as AI-driven autonomous systems and IoT-based smart transportation networks, to enhance its effectiveness.	15	CO3	4

*Standard Units, $h = 1.602 \times 10^{-19}$ J.s and Speed of Light, $C = 3 \times 10^8$ m/s