



School of Computer Science and Engineering

Winter Semester 2023-24

Continuous Assessment Test – I1

SLOT: A1+TA1

Programme Name & Branch: B.Tech (CSE)

Course Name & Code: Embedded Systems – BCSE305L

Class Number (s):

Faculty Name (s): All

Exam Duration: 90 Min.

Maximum Marks: 50

Q.No.	Question	Max Marks	CO	BL																																
1.	<p>Using relevant real life examples, investigate how events or signals could be classified as per the following criteria and provide sufficient justifications:-</p> <ol style="list-style-type: none"> Arrival Form or Structure Type (hint: what it conveys?) 	10	CO4	BL4																																
2.	<p>Discover and discuss in details regarding the requirements of real-time embedded systems. Design and demonstrate a hybrid scheduler for an embedded system governed by the real time requirements.</p> <p>Note: Hybrid scheduler must be illustrated using sample dataset of your choice, Task-Time line graph, and the necessary as well as sufficient conditions.</p>	10	CO4	BL3																																
3.	<p>For the given datasets, prove that EDF gives feasible schedule. Illustrate task time-line graph for at least three cycles.</p> <table border="1" data-bbox="311 1512 1037 1646"> <thead> <tr> <th>Task</th> <th>Execution Time</th> <th>Period</th> </tr> </thead> <tbody> <tr> <td>T1</td> <td>5</td> <td>15</td> </tr> <tr> <td>T2</td> <td>7</td> <td>10</td> </tr> <tr> <td>T3</td> <td>10</td> <td>20</td> </tr> </tbody> </table> <p>Compute the utilization percentage for the following data set using EDF technique and identify the parameters required to be manipulated for better utilization and schedulability with proper justifications.</p> <table border="1" data-bbox="311 1825 1037 1982"> <thead> <tr> <th>Task</th> <th>Arrival Time</th> <th>Execution Time</th> <th>Period</th> <th>Deadline</th> </tr> </thead> <tbody> <tr> <td>T1</td> <td>0</td> <td>5</td> <td>20</td> <td>20</td> </tr> <tr> <td>T2</td> <td>5</td> <td>10</td> <td>15</td> <td>15</td> </tr> <tr> <td>T3</td> <td>10</td> <td>15</td> <td>10</td> <td>10</td> </tr> </tbody> </table>	Task	Execution Time	Period	T1	5	15	T2	7	10	T3	10	20	Task	Arrival Time	Execution Time	Period	Deadline	T1	0	5	20	20	T2	5	10	15	15	T3	10	15	10	10	10	CO4	BL3
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	<p>➤ “Fruit Classifier”</p> <p>Specification:</p> <ol style="list-style-type: none"> 1. Ambience:-Agro market with fruit sorting, pricing and packing using multiple robots 2. Baskets of different types 3. Different types of fruits such as watermelon, apple, pomegranate, grapes etc. 4. Mobile robot with 360⁰ rotational arm capability <p>Requirements:</p> <ol style="list-style-type: none"> 1. Fruits need to be sorted based on type, size, quality and weight 2. Collision avoidance to be incorporated 3. Relevant states, events and actions to be considered <p>Illustrate the CDFG for the above scenario.</p>			
5.	<p>Identify as well as analyse the requirements of code optimization in embedded system design.</p> <p>Apply your findings on the given code snippet to get the optimized code with relevant validations</p> <pre> int p; int q=50; int r=100; for (inti=0; i<200; i++) { int w = 25 + 35; p = q + r; for (inti=0; i<200; i++) Temperature[i] = i * 2; for (inti=0; i<200; i++) Moisture[i] = i * 3; } </pre>	10	CO3	BL2



School of Computer Science and Engineering
Winter Semester 2023-24

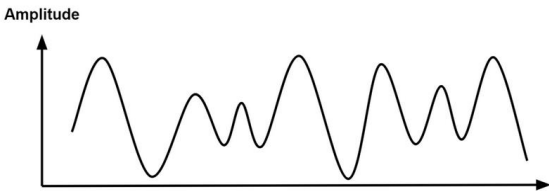
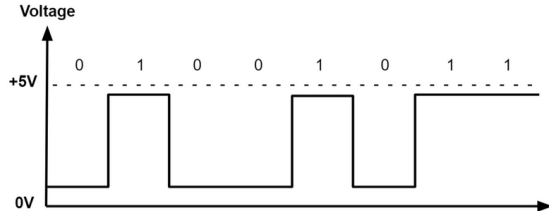
Continuous Assessment Test – II

Programme Name & Branch:B.Tech (CSE) **SLOT:** A1+TA1

Course Name & Code: Embedded Systems – BCSE305L

Class Number (s): **Faculty Name (s):** All

Exam Duration: 90 Min. **Maximum Marks:** 50

Q. No.	Questions	Keys
1.	<p>Note: The evaluation must be based on the individual answers. The keys are provided just for the reference</p> <p>Using relevant real life examples, investigate how events or signals could be classified as per the following criteria and provide sufficient justifications:-</p> <ol style="list-style-type: none"> Arrival Form or Structure Type (hint: what it conveys?) 	<p>a. Arrival –</p> <ul style="list-style-type: none"> Periodic – ex: Time Table, Flickering of a fluorescent light, etc. Aperiodic – ex: Activation of a door bell Sporadic – ex: Government town bus in a remote village <p>b. Form / Structure –</p> <p>Analog – Systems for communicating voice, data, picture, signal, and video information frequently use analog signal which is provide continuous transmissions. Any physical phenomena - sound, light, temperature, position, or pressure</p>  <p>Digital - All digital electronics, including computer hardware and data transfer devices, rely on digital signals. Ex: Voltage, current, magnetic field and any physical quantity</p>  <p>c. Type (What it conveys...) –</p> <ul style="list-style-type: none"> Text / Message – Remote water pump control via mobile device Audio – Ex: Voice signal – voice operated ATM Video / image – Ex: Attendance system using facial recognition

<p>2.</p>	<p>Discover and discuss in details regarding the requirements of real-time embedded systems. Design and demonstrate a hybrid scheduler for an embedded system governed by the real time requirements.</p> <p>Note: Hybrid scheduler must be illustrated using sample dataset of your choice, Task-Time line graph, and the necessary as well as sufficient conditions.</p>	<p>Requirements of a real time embedded systems:</p> <ul style="list-style-type: none"> • Functional correctness - Producing correct computational output • Timeliness – meeting time deadline • Scalability – consistent behavior of the system irrespective of scale • Cost effectiveness – loss of life or property or performance <p>Note: apply and discuss in detail these factors for a real life example such as – Anti-Missile Launching System, Nuclear Reactor Power Control, Driverless Automobile, and Smart Class Room etc.</p> <p>Hybrid Scheduler: Event Driven Scheduler – Minimum Laxity/Slack First using relative deadline and remaining execution to calculate the priority for tasks</p>																																
<p>3.</p>	<p>For the given datasets, prove that EDF gives feasible schedule. Illustrate task time-line graph for at least three cycles.</p> <table border="1" data-bbox="169 857 895 987"> <thead> <tr> <th>Task</th> <th>Execution Time</th> <th>Period</th> </tr> </thead> <tbody> <tr> <td>T1</td> <td>5</td> <td>15</td> </tr> <tr> <td>T2</td> <td>7</td> <td>10</td> </tr> <tr> <td>T3</td> <td>10</td> <td>20</td> </tr> </tbody> </table> <p>Compute the utilization percentage for the following data set using EDF technique and identify the parameters required to be manipulated for better utilization and schedulability with proper justifications.</p> <table border="1" data-bbox="169 1171 895 1330"> <thead> <tr> <th>Task</th> <th>Arrival Time</th> <th>Execution Time</th> <th>Period</th> <th>Deadline</th> </tr> </thead> <tbody> <tr> <td>T1</td> <td>0</td> <td>5</td> <td>20</td> <td>20</td> </tr> <tr> <td>T2</td> <td>5</td> <td>10</td> <td>15</td> <td>15</td> </tr> <tr> <td>T3</td> <td>10</td> <td>15</td> <td>10</td> <td>10</td> </tr> </tbody> </table>	Task	Execution Time	Period	T1	5	15	T2	7	10	T3	10	20	Task	Arrival Time	Execution Time	Period	Deadline	T1	0	5	20	20	T2	5	10	15	15	T3	10	15	10	10	<p>Apply EDF schedulability check</p> <p>First tasks set – schedulability fails and Illustrate time line graph Note: Analysis of cases based on user assumed arrival time of tasks for schedulability, may be considered</p> <p>Second tasks set – schedulability fails Analysis of correct parameters for feasible schedule with justifications and illustration Example:</p> <ul style="list-style-type: none"> • Manipulation (increment or decrement) of execution time of a task - Execution time of tasks T2 and T3 can be reduced Note: manipulation of execution time can be achieved by applying optimization in code, increasing cache and faster communication buses • Since arrival time and period of tasks purely depends on scenario and natural phenomena, they should not be modified • Since deadline is user defined, it may be modified.
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<p>4.</p>	<p>Construct FSM model for the given scenario: - ➤ “Fruit Classifier”</p> <p>Specification:</p> <ol style="list-style-type: none"> 1. Ambience:-Agro market with fruit sorting, pricing and packing using multiple robots 2. Baskets of different types 3. Different types of fruits such as watermelon, apple, pomegranate, grapes etc. 4. Mobile robot with 360⁰ rotational arm capability <p>Requirements:</p> <ol style="list-style-type: none"> 1. Fruits need to be sorted based on type, size, quality and weight 2. Collision avoidance to be incorporated 3. Relevant states, events and actions to be considered <p>Illustrate the CDFG for the above scenario.</p>	<p>Entity</p> <ul style="list-style-type: none"> • Agro Market • types of fruits and baskets • mobile robots <p>Fruits</p> <ul style="list-style-type: none"> • number of fruits • types • price-tag • size • weight • quality <p>Basket</p> <ul style="list-style-type: none"> • Empty • Large • Medium • small • full 																																

Robot

- idle
- move-forward
- move-backward
- turn-left
- turn-right
- arm-rotate(360⁰)
- pick
- sort
- place
- halt

From State	Event	To State
Idle	Pick basket/fruit/sort/place/basket-empty/basket-full/obstacle-true/obstacle-false or any other	Move-forward/Move-backward/ Turn-left/ Turn-right
Move-forward/Move-backward/ Turn-left/ Turn-right	sort/price-tag/place	Halt

Note: Consider all possible states and events and draw the FSM

5. **Identify as well as analyse** the requirements of code optimization in embedded system design.

Apply your findings on the given code snippet to get the optimized code with relevant validations

```
int p;
int q=50;
int r=100;
for (inti=0; i<200; i++)
{
int w = 25 + 35;
p = q + r;
for (inti=0; i<200; i++)
Temperature[i] = i * 2;

for (inti=0; i<200; i++)
Moisture[i] = i * 3;
}
```

Requirements of code optimization

- Constrained resources
 - a. Memory
 - b. Processing
 - c. Power
- Design Challenges
 - a. Time and space complexity
 - b. Scalability – features
 - c. Cost optimization
 - d. Time to market – customization, faster portability, backward compatibility

Optimization Techniques:

- Constant folding
- Code motion
- Sub expression evaluation
- Loop fusion
- Strength reduction
- Replacing array access using pointer