

9. Find standard basis vector/vectors that can be added to the following set of vectors to produce a basis for \mathbb{R}^3 and \mathbb{R}^4 .

(i) $\mathbf{v}_1 = (1, -1, 0), \mathbf{v}_2 = (3, 1, -2)$

(ii) $\mathbf{v}_1 = (1, -2, 5, -3), \mathbf{v}_2 = (2, 3, 1, -4)$

$$\left[\begin{array}{l} \text{Ans.:} \\ \text{one possible basis} \\ \text{(i) } \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_1\} \quad \text{(ii) } \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{e}_3, \mathbf{e}_4\} \end{array} \right]$$

2.12 COORDINATE VECTOR RELATIVE TO A BASIS

If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ is a basis for a vector space V then any vector \mathbf{v} in V can be expressed as

$$\mathbf{v} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + \dots + k_n \mathbf{v}_n$$

The scalars k_1, k_2, \dots, k_n are called the coordinates of \mathbf{v} relative to the basis S and the vector (k_1, k_2, \dots, k_n) in \mathbb{R}^n is called the coordinate vector of \mathbf{v} relative to S . This vector is denoted by

$$(\mathbf{v})_S = (k_1, k_2, \dots, k_n)$$

Note: The coordinate vectors depend on the order in which the basis vectors are written. If the order of the basis vectors is changed, a corresponding change of order occurs in the coordinate vectors.

Example 1: Find the coordinate vector of \mathbf{v} relative to the basis S .

(i) $\mathbf{v} = (1, 1); S = \{\mathbf{v}_1, \mathbf{v}_2\}$ where $\mathbf{v}_1 = (2, -4), \mathbf{v}_2 = (3, 8)$

(ii) $\mathbf{v} = (5, -12, 3); S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ where $\mathbf{v}_1 = (1, 2, 3), \mathbf{v}_2 = (-4, 5, 6), \mathbf{v}_3 = (7, -8, 9)$

Solution: (i) Let

$$(\mathbf{v})_S = (k_1, k_2)$$

$$\mathbf{v} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2$$

$$(1, 1) = k_1(2, -4) + k_2(3, 8)$$

$$= (2k_1 + 3k_2, -4k_1 + 8k_2)$$

Equating corresponding components,

$$2k_1 + 3k_2 = 1$$

$$-4k_1 + 8k_2 = 1$$

Solving these equations,

$$k_1 = \frac{5}{28}, k_2 = \frac{3}{14}$$

Hence, $(\mathbf{v})_S = \left(\frac{5}{28}, \frac{3}{14} \right)$

(ii) Let

$$(\mathbf{v})_S = (k_1, k_2, k_3)$$

$$\mathbf{v} = k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3$$

$$(5, -12, 3) = k_1(1, 2, 3) + k_2(-4, 5, 6) + k_3(7, -8, 9)$$

$$= (k_1 - 4k_2 + 7k_3, 2k_1 + 5k_2 - 8k_3, 3k_1 + 6k_2 + 9k_3)$$

Equating corresponding components,

$$\begin{aligned}k_1 - 4k_2 + 7k_3 &= 5 \\2k_1 + 5k_2 - 8k_3 &= -12 \\3k_1 + 6k_2 + 9k_3 &= 3\end{aligned}$$

Solving these equations,

$$k_1 = -2, k_2 = 0, k_3 = 1$$

Hence, $(\mathbf{v})_S = (-2, 0, 1)$

Example 2: Find the coordinate vector of $\mathbf{p} = 2 - x + x^2$ relative to the basis $S = \{\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3\}$ where $\mathbf{p}_1 = 1 + x$, $\mathbf{p}_2 = 1 + x^2$, $\mathbf{p}_3 = x + x^2$.

Solution: Let $(\mathbf{p})_S = (k_1, k_2, k_3)$

$$\mathbf{p} = k_1\mathbf{p}_1 + k_2\mathbf{p}_2 + k_3\mathbf{p}_3$$

$$\begin{aligned}2 - x + x^2 &= k_1(1 + x) + k_2(1 + x^2) + k_3(x + x^2) \\&= (k_1 + k_2) + (k_1 + k_3)x + (k_2 + k_3)x^2\end{aligned}$$

Equating corresponding coefficients,

$$\begin{aligned}k_1 + k_2 &= 2 \\k_1 + k_3 &= -1 \\k_2 + k_3 &= 1\end{aligned}$$

Solving these equations,

$$k_1 = 0, k_2 = 2, k_3 = -1$$

Hence, $(\mathbf{p})_S = (0, 2, -1)$

Example 3: Find the coordinate vector of A relative to the basis $S = \{A_1, A_2, A_3, A_4\}$, where

$$\begin{aligned}A &= \begin{bmatrix} 2 & 0 \\ -1 & 3 \end{bmatrix}, A_1 = \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix}, A_2 = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \\A_3 &= \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, A_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\end{aligned}$$

Solution: Let $(A)_S = (k_1, k_2, k_3, k_4)$

$$A = k_1A_1 + k_2A_2 + k_3A_3 + k_4A_4$$

$$\begin{aligned}\begin{bmatrix} 2 & 0 \\ -1 & 3 \end{bmatrix} &= k_1 \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} + k_2 \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} + k_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + k_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \\&= \begin{bmatrix} -k_1 + k_2 & k_1 + k_2 \\ k_3 & k_4 \end{bmatrix}\end{aligned}$$

Equating corresponding components,

$$\begin{aligned} -k_1 + k_2 &= 2 \\ k_1 + k_2 &= 0 \\ k_3 &= -1 \\ k_4 &= 3 \end{aligned}$$

Solving these equations,

$$k_1 = -1, k_2 = 1, k_3 = -1, k_4 = 3$$

Hence, $(A)_S = (-1, 1, -1, 3)$

Example 4: The vectors $\mathbf{v}_1 = (1, -1, 1)$, $\mathbf{v}_2 = (0, 1, 2)$, $\mathbf{v}_3 = (3, 0, -1)$ form a basis of V . Let $S_1 = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and $S_2 = \{\mathbf{v}_3, \mathbf{v}_2, \mathbf{v}_1\}$ are different orderings of these vectors. Determine the vector \mathbf{v} in V having following coordinate vectors.

- (i) $(\mathbf{v})_{S_1} = (3, -1, 8)$
(ii) $(\mathbf{v})_{S_2} = (3, -1, 8)$

Solution: (i) $S_1 = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and $k_1 = 3, k_2 = -1, k_3 = 8$

$$\begin{aligned} \mathbf{v} &= k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 \\ &= 3(1, -1, 1) - 1(0, 1, 2) + 8(3, 0, -1) \\ &= (3 + 24, -3 - 1, 3 - 2 - 8) \\ \mathbf{v} &= (27, -4, -7) \end{aligned}$$

(ii) $S_2 = \{\mathbf{v}_3, \mathbf{v}_2, \mathbf{v}_1\}$ and $k_1 = 3, k_2 = -1, k_3 = 8$

$$\begin{aligned} \mathbf{v} &= k_1 \mathbf{v}_3 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_1 \\ &= 3(3, 0, -1) - 1(0, 1, 2) + 8(1, -1, 1) \\ &= (9 + 8, -1 - 8, -3 - 2 + 8) \\ \mathbf{v} &= (17, -9, 3) \end{aligned}$$

In this example we observe that on changing the order of vectors in the basis, we get two different vectors in V corresponding to same coordinate vectors.

Coordinate Matrices

If $(\mathbf{v})_S = (k_1, k_2, \dots, k_n)$ is the coordinate vector of \mathbf{v} relative to the basis S then the coordinate matrix of \mathbf{v} relative to the basis S is defined as

$$[\mathbf{v}]_S = \begin{bmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{bmatrix}$$