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import graphviz
```

```
class Element:
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```
    def __init__(self, data, priority):
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        self.data = data
```

```
        self.priority = priority
```

```
i = 0
```

```
class PriorityQueue:
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    def __init__(self, size) -> None:
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```
        self.size = size
```

```
        self.heap = []
```

```
    def shift_up(self):
```

```
        global i
```

```
        if len(self.heap) == 1:
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```
            return
```

```
        last_idx = len(self.heap) - 1
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        self.display_as_graph(f"pq_enq_{i}")
```

```
        i += 1
```

```
        while last_idx > 0:
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            parent_idx = (last_idx - 1) >> 1 #
```

```
            if (self.heap[parent_idx].priority < self.heap[last_idx].priority) or (
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```
                self.heap[parent_idx].priority == self.heap[last_idx].priority
```

```
                and self.heap[parent_idx].data < self.heap[last_idx].data
```

```
            ):
```

```
                self.heap[last_idx], self.heap[parent_idx] = (
```

```
                    self.heap[parent_idx],
```

```
                    self.heap[last_idx],
```

```
                )
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        self.display_as_graph(f"pq_enq_{i}")

        i += 1

    last_idx = parent_idx


def enqueue(self, item: Element):
    if len(self.heap) == self.size:
        print("Cannot Enqueue. Queue is full")
        return

    self.heap.append(item)
    self.shift_up()


def shift_down(self, index: int):
    global i

    left = (index << 1) + 1
    right = (index << 1) + 2
    largest = index

    if left < len(self.heap) and self.heap[left].priority > self.heap[largest].priority:
        largest = left

    elif left < len(self.heap) and self.heap[largest].priority == self.heap[largest].priority:
        if self.heap[left].data > self.heap[largest].data:
            largest = left

    if right < len(self.heap) and self.heap[right].priority > self.heap[largest].priority:
        largest = right

    elif right < len(self.heap) and self.heap[right].priority == self.heap[largest].priority:
        if self.heap[right].data > self.heap[largest].data:
            largest = right

    if largest != index:

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self.heap[largest], self.heap[index] = self.heap[index], self.heap[largest]

self.display_as_graph(f"pq_d_{i}")

i += 1

self.shift_down(largest)

```

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def dequeue(self) -> Element | None:

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    global i

    if len(self.heap) == 0 or self.size == 0:

        print("Cannot dequeue. Queue is empty")

        return None

    self.heap[0], self.heap[len(self.heap) - 1] = self.heap[len(self.heap) - 1], self.heap[0]

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    element = self.heap.pop()

    self.display_as_graph(f"pq_d_{i}")

    i += 1

    self.shift_down(0)

    self.size -= 1

    return element

```

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def peek(self) -> Element:

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    return self.heap[0]

```

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def display(self):

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    if len(self.heap) == 0:

        print("Empty queue")

        return

    for i in self.heap:

        print(f"({i.data}, {i.priority})", end=" ")

    print()

```

```

def display_as_graph(self, filename):

```

```

dot = graphviz.Digraph(format='png')

for i, element in enumerate(self.heap):
    dot.node(f'node_{i}', f'{element.data},{element.priority}')

for i, element in enumerate(self.heap):
    left_child_idx = 2 * i + 1
    right_child_idx = 2 * i + 2

    if left_child_idx < len(self.heap):
        dot.edge(f'node_{i}', f'node_{left_child_idx}')

    if right_child_idx < len(self.heap):
        dot.edge(f'node_{i}', f'node_{right_child_idx}')

dot.render(filename, cleanup=True)

if __name__ == '__main__':
    pq = PriorityQueue(10)
    pq.display()
    pq.enqueue(Element(10, 1))
    pq.display()
    pq.enqueue(Element(14, 0))
    pq.display()
    pq.enqueue(Element(16, 4))
    pq.display()
    pq.enqueue(Element(12, 5))
    pq.display()
    pq.enqueue(Element(34, 20))
    pq.display()
    pq.enqueue(Element(100, 3))

```

```
pq.display()  
pq.enqueue(Element(8, 20))  
pq.enqueue(Element(85, 20))  
pq.display_as_graph("pq_before_dequeue")  
pq.dequeue()  
pq.display_as_graph("pq")
```