



VIT[®]

Vellore Institute of Technology
(Deemed to be University under section 3 of UGC Act, 1956)

REG.NO.:

NAME OF THE SCHOOL: SCHEME
CONTINUOUS ASSESSMENT TEST - II
FALL SEMESTER 2024-2025

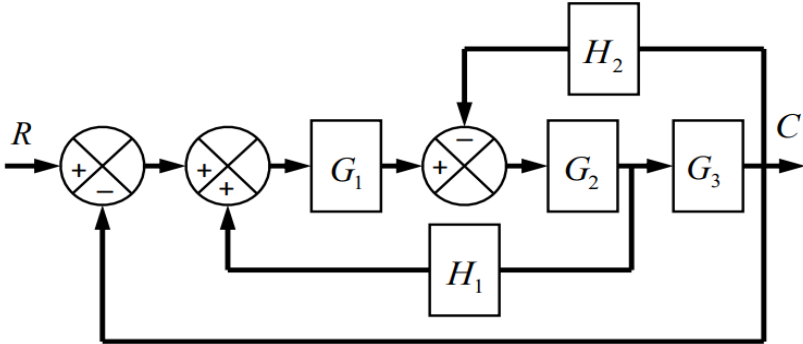
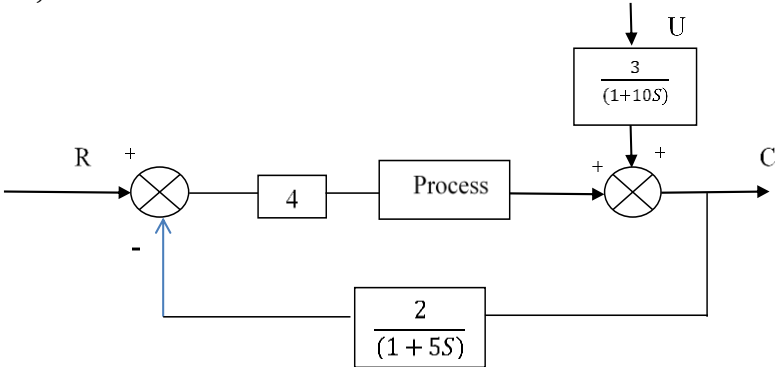
SLOT: B1+TB1

Programme Name & Branch : B.TECH & Chemical Engineering
 Course Code and Course Name : BCHE305L and Process Dynamics and Control
 Faculty Name(s) : Dr.A. Babu Ponnusami
 Class Number(s) : VL2024250103163
 Date of Examination : 14-10-24
 Exam Duration : 90 minutes

Maximum Marks: 50

General instruction(s):

- Answer All Questions
 - M - Max mark; CO – Course Outcome; BL – Blooms Taxonomy Level (1 – Remember, 2 – Understand, 3 – Apply, 4 – Analyse, 5 – Evaluate, 6 – Create)
 - Course Outcomes (Type the CO statements covered in this question paper. Use the CO number as per the syllabus copy)
3. Identify the modes of control action required for closed loop control system and its stability in time domain.

Q. No	Question	M	CO	BL
1.	Obtain the transfer function for the following block diagram using block diagram reduction techniques 	10	3	B L 3
2.	For the control system shown in fig analyse offset values that results due to unit step change in 'U' when the process transfer function is (i) $\frac{1}{1+12s}$ and (ii) $\frac{1}{s(1+12s)}$ 	10	3	B L 4



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3.	a) A PID controller is at steady state with an output pressure of 9 psi . The set point and pen point are initially together. At time t=0, the set point is moved away from the pen point at a rate of 0.5 inch/min. If the knob settings are $K_c = 2$ psi/inch, $\tau_i = 1.25$ min and $\tau_D = 0.4$ min. Plot the output pressure versus time.	5	3	B L 3
	b) A Pneumatic temperature controller has an output range of 3 to 15 psi and a chart calibration of 0-200°C. If the output is 6 psi at 70°C, determine the proportional sensitivity when proportional band is 25% and the output at 100°C.	5		
4.	(a) A unit step change is given to PI controller. If the proportional sensitivity or gain K_c is 4, the integral time τ_i is 2, Obtain the response of the PI controller.	5	3	B L 3
	(b) Under what circumstances proportional controller is consider as ON/OFF controller. A pneumatic proportional controller is used to control temperature within the range of 60°F to 110°F. The controller is adjusted so that the input pressure goes from 3 psi (fully open) to 15 psi (fully closed). Measured temperature goes from 76-80°F with set point set as constant. Calculate the gain and proportional band.	5		
5.	A feedback control system has the following transfer functions: Process : $G_p(S) = \frac{5}{[(2s+1)(s+1)]}$ Measurement: $H(s) = \frac{1}{(0.5s+1)}$ Final control element : $G_v(s) = \frac{0.2}{(0.1s+1)}$ Controller : $G_c(s) = K_c$ Using Routh's stability criterion obtain the range of K_c value for which the system is stable.	10	3	B L 3

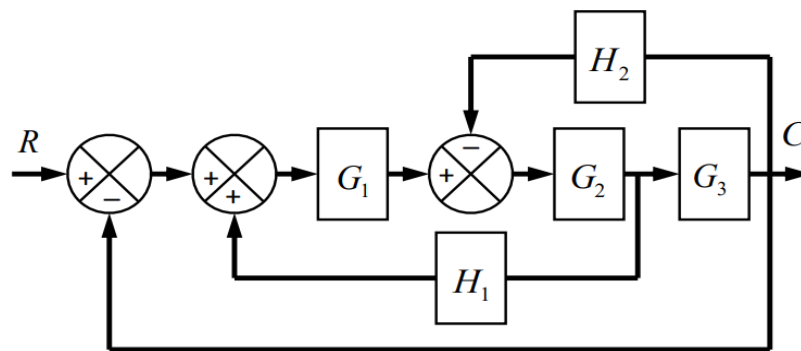
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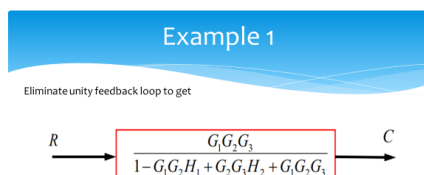
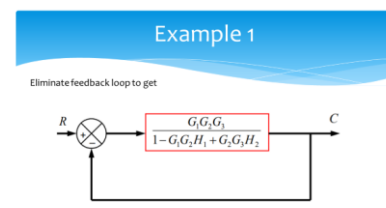
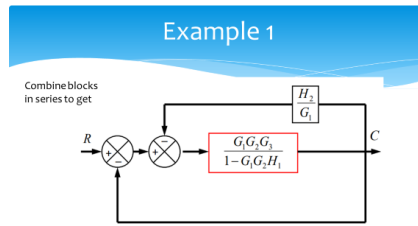
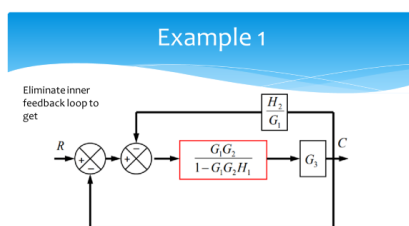
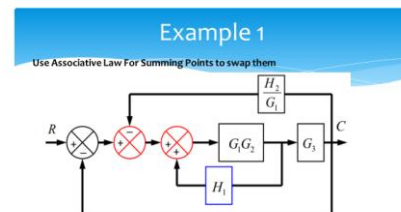
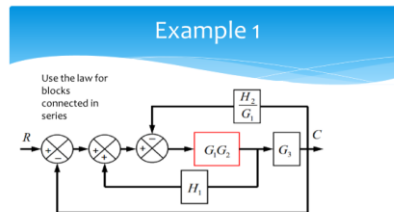
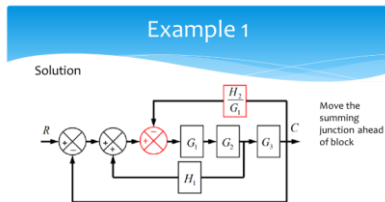
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Answer Key

1. Obtain the transfer function for the following block diagram using block diagram reduction techniques



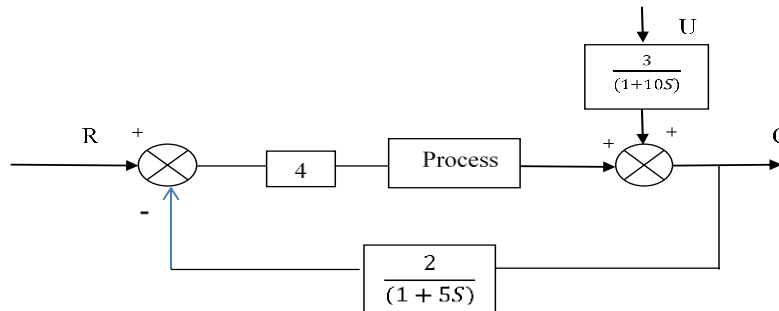
Ans:



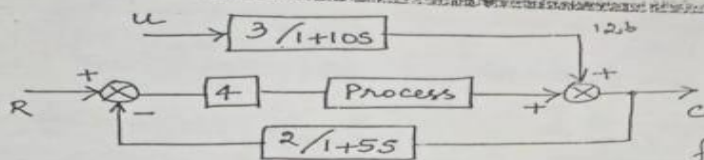
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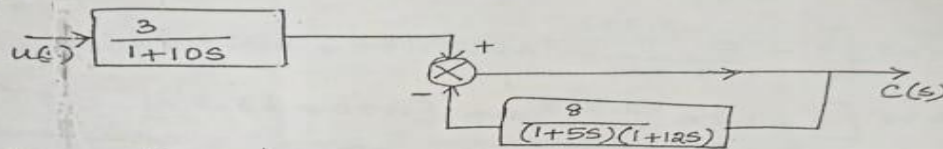
2. For the control system shown in Fig find the offset that results due to unit step change in 'U' when the process transfer function is (i) $\frac{1}{1+12s}$ and (ii) $\frac{1}{s(1+12s)}$



Ans:



i) when the process transfer function is $\frac{1}{1+12s}$ & for a unit step change in u ,



$$\frac{C(s)}{u(s)} = \left[\frac{1}{1 + \frac{8}{(1+5s)(1+12s)}} \right] \frac{3}{1+10s}$$

$$\frac{C(s)}{u(s)} = \frac{3(60s^2 + 17s + 1)}{(1+10s)(60s^2 + 17s + 9)}$$

for a unit step change in u ,

$$C(s) = \frac{3(60s^2 + 17s + 1)}{s(1+10s)(60s^2 + 17s + 9)}$$

$$\therefore \text{offset} = C_{sp}(\infty) - C(\infty)$$

$$\text{where } C(\infty) = \lim_{s \rightarrow 0} s C(s) = \lim_{s \rightarrow 0} s \left[\frac{3(60s^2 + 17s + 1)}{s(1+10s)(60s^2 + 17s + 9)} \right]$$

$$C(\infty) = \frac{3}{9} = \frac{1}{3}$$

$$\therefore \text{offset} = 0 - \frac{1}{3} = -\frac{1}{3}$$

ii) when the process transfer function is $\frac{1}{s(1+12s)}$,

$$\frac{C(s)}{u(s)} = \left[\frac{1}{1 + \frac{8}{s(1+5s)(1+12s)}} \right] \frac{3}{1+10s}$$

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$$\frac{C(s)}{U(s)} = \frac{3s(60s^2 + 17s + 1)}{[s(60s^2 + 17s + 1) + 8](1 + 10s)}$$

$$C(s) = \frac{3s(60s^2 + 17s + 1)}{s[(60s^3 + 17s^2 + s + 8)(1 + 10s)]}$$

$$\therefore \text{offset} = 0 - \lim_{s \rightarrow 0} \frac{3s(60s^2 + 17s + 1)}{(60s^3 + 17s^2 + s + 8)(1 + 10s)}$$

$$= 0 - 0 = 0$$

3. a) A PID controller is at steady state with an output pressure of 9 psi. The set point and pen point are initially together. At time $t=0$, the set point is moved away from the pen point at a rate of 0.5 inch/min. If the knob settings are $K_c = 2$ psi/inch, $\tau_i = 1.25$ min and $\tau_D = 0.4$ min. Plot the output pressure versus time.

Ans:

Ex. P. 2. A PID control is at steady state with an output pressure of 9 psi. The set point & pen point are initially together. At time $t=0$, the set point is moved away from the pen point at a rate of 0.5 inch/min. If the knob settings are $K_c = 2$ psi/inch, $\tau_i = 1.25$ min & $\tau_D = 0.4$ min. Plot the output pressure versus time.

Solution:

Given Data:

$p_0 = 9$ psi, $K_c = 2$, $\tau_i = 1.25$, $\tau_D = 0.4$.

$e(t) = 0.5t$

The PID controller equation is,

$$P(s) = K_c \left[1 + \frac{1}{\tau_i s} + \tau_D s \right] E(s)$$

where $E(s) = \frac{0.5}{s^2}$

$$\therefore P(s) = \frac{2 \times 0.5}{s^2} \left[1 + \frac{1}{1.25s} + 0.4s \right]$$

$$P(s) = \frac{1}{s^2} + \frac{1}{1.25s^3} + \frac{0.4}{s}$$

The inversion of above equation results in

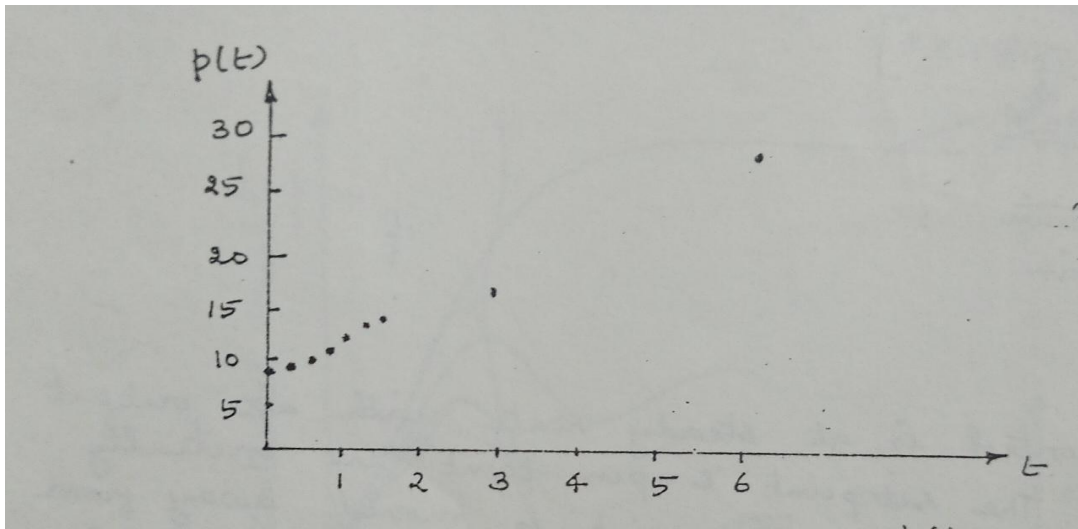
$$p(t) = t + 0.4t^2 + 0.4 + 9$$

The plot of output pressure versus time is obtained using table given below & shown in fig. 2.

t	0	0.2	0.4	0.6	0.8	1	1.25	1.5	3	6
p(t)	9.4	9.616	9.864	10.14	10.456	10.8	11.27	11.8	16	29.1

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b) A Pneumatic temperature controller has an output range of 3 to 15 psi and a chart calibration of 0-200°C. If the output is 6 psi at 70°C, determine the proportional sensitivity when proportional band is 25% and the output at 100°C.

Ans:

Ex. P.
2.15

A pneumatic ^{temp} controller has an o/p range of 3 to 15 lb/in² & a chart calibration of 0-200°C. If the o/p is 6 lb/in² at 70°C, determine the proportional sensitivity when PB is 25% & the o/p at 100°C & 125°C.

Solution:

$$PB = \frac{\text{measured Variable}}{\text{scale range}}$$

$$0.25 \times 200 = \text{measured Variable (or) temp change}$$

$$\therefore \text{temp change} = 50$$

$$\text{sensitivity (Kp)} = \frac{\text{change in o/p}}{\text{temp change}} = \frac{15-3}{50} = 0.24 \frac{\text{psi}}{^\circ\text{C}}$$

The controller eqn. is

$$p = K_p e + p_0$$

$$\therefore 6 = 0.24 \times 70 + p_0 \Rightarrow p_0 = -10.8$$

hence o/p pressure at 100°C = $0.24 \times 100 - 10.8 = 13.2 \text{ psi}$

4. (a) A unit step change is given to PI controller. If the proportional sensitivity or gain K_c is 4, the integral time τ_I is 2, Obtain the response of the PI controller.

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(b) Under what circumstances proportional controller is consider as ON/OFF controller. A pneumatic proportional controller is used to control temperature within the range of 60°F to 110°F. The controller is adjusted so that the input pressure goes from 3 psi (fully open) to 15 psi (fully closed). Measured temperature goes from 76-80°F with set point set as constant. Find the gain and proportional band.

Ans:

a)

$$\frac{P(s)}{E(s)} = K_c \left(1 + \frac{1}{T_I s} \right)$$

$$G(s) = \frac{1}{s}$$

$$P(s) = \frac{K_c}{s} \left(1 + \frac{1}{T_I s} \right)$$

where $K_c = 4$, $T_I = 2$.

$$P(s) = \frac{4}{s} \left(1 + \frac{1}{2s} \right) \Rightarrow \frac{4}{s} + \frac{2}{s^2}$$

$$\boxed{P(t) = 4 + 2t}$$

b) At higher values of Proportional gain, Proportional Controller consider as ON/OFF Controller.

Range of Controller 60-110°F

Change in Pressure, $\Delta P = 3\text{psi} - 15\text{psi}$

measured temp range, $\Delta T = 76 - 80^\circ\text{F}$

$$\text{Proportional gain} = \frac{\Delta P}{\Delta T} = \frac{15 - 3}{80 - 76} = \frac{12}{4} = 3 \text{ psi/}^\circ\text{F}$$

$$\text{Proportional band} = \frac{80 - 76}{15 - 3} = \frac{4}{12} \times 100 = 8\%$$

5. Process : $G_p(s) = \frac{5}{[(2s+1)(s+1)]}$
 Measurement: $H(s) = \frac{1}{(0.5s+1)}$
 Final control element : $G_v(s) = \frac{0.2}{(0.1s+1)}$
 Controller : $G_c(s) = K_c$

Using Routh's stability criterion range of K_c value for which the system is stable.

Ans:

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(7)

$1 + G = 0$, $1 + C_1 K \cdot C_{DVC} H = 0$

$= 1 + \frac{5}{(2s+1)(s+1)} \times \frac{1}{(0.5ss)} \times \frac{0.2}{(0.1s+1)} K_c = 0$

$= 1 + \frac{5/2}{(s+0.5)(s+1)} \times \frac{9}{s^2} \times \frac{2-s}{s+10} K_c = 0$

$\Rightarrow 1 + \frac{10Kc}{(s+1)(s+2)(s+0.5)(s+10)} = 0$

$\xrightarrow{\quad\quad\quad}$ $(s^2+3s+2)(s^2+s+5) = s^4 + 10.5s^3 + 5s^2 + 35 + 31.5s^2 + 18s + 2s^2 + 10s + 10$

$= s^4 + 13.5s^3 + 38.5s^2 + 65.5s + 10$

$\Rightarrow 1 + \frac{10Kc}{s^4 + 13.5s^3 + 38.5s^2 + 65.5s + 10} = 0$

$\Rightarrow s^4 + 13.5s^3 + 38.5s^2 + 65.5s + 10 + 10Kc = 0$

$0.1s^4 + 1.35s^3 + 3.85s^2 + 6.5s + (1+Kc) = 0$

s ⁴	0.1	38.5	10 + 10Kc
s ³	1.35	-3.6	
s ²	4.83	1 + Kc	
s ¹	17.34	-1.35 - 1.35Kc	
s ⁰	⇒ (4.83 - 1.35Kc)/4.83		
s	1 + Kc		

— (4) makes

For the system to be stable, S has a sign > 0.

a' ⇒ $\frac{15.99}{4.83} - 1.35Kc > 0$ $15.99 > 1.35Kc$ $11.84 < Kc < 200$

b' ⇒ $1 + Kc > 0$ $Kc > -1$ (or) $Kc > 0$

∴ $[0 < Kc < 11.84]$ — 2 marks