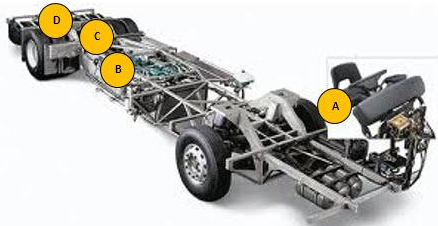
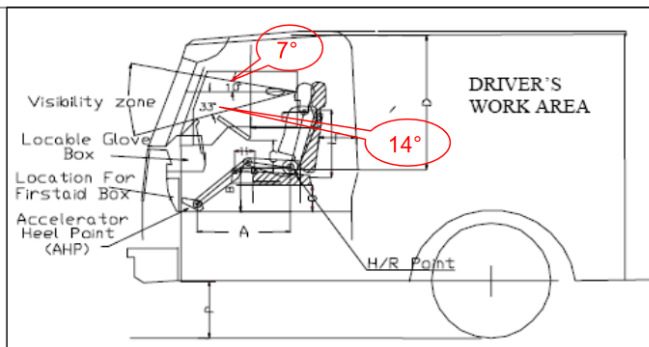


 VIT[®] Vellore Institute of Technology (Deemed to be University under section 3 of the UGC Act, 1956)	Final Assessment Test – Winter 2024-25 Semester - Apr 2025					
	Course code : BMEE414L				Slot : A2 + TA2	
	Course Title : Vehicle Body and Aerodynamics Engineering				Time: Three Hours	
	Class Number(s) : VL2024250503868				Max. Marks: 100	
	Faculty Name : Dr. Y. Mukkamala				School: SMEC	
	Emp Id : yagnasmukkamala@vit.ac.in				Mobile No.: 9345310732	
KEEPING MOBILE PHONE/ANY ELECTRONIC GADGETS, EVEN IN ‘OFF’ POSITION IS TREATED AS EXAM MALPRACTICE						
General Instructions if any:						
1. Non Programmable calculator is permitted : YES /NO						
2. Reference tables are permitted : YES / NO (if Yes, Please specify:)						
Answer ALL Questions (10 X 10 = 100 Marks)						
Sl. No:	Questions	Module No	Marks	CO	BL	E/A/T
1.	Bus chassis: Ladder frame  Tubular space-frame:  Driver seat and visibility:	1	10	1	3	T



Dimensional Requirements:

A Distance from Heel Point to “H” Point 600 mm to 640 mm

B Minimum Distance from floor to “H” Point with the driver’s seat in the upper most position
500 mm

C Thigh Clearance 200 mm to 260 mm

D Minimum Distance from “H” Point to Roof top 1060 mm

E Minimum Distance from the lower end of steering to the front of driver’s seat back rest 350 mm

F Minimum Distance of driver’s partition from the rear of the driver’s seat with the driver’s seat in the rear most Position 25 mm

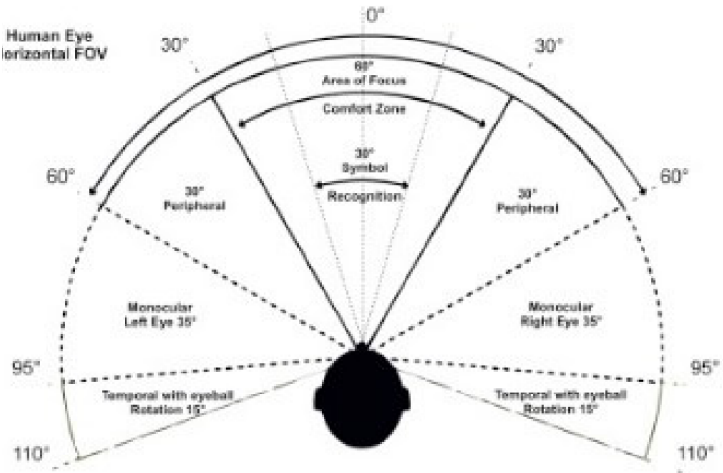
Windshield: A clean and clear windshield is essential for optimal visibility

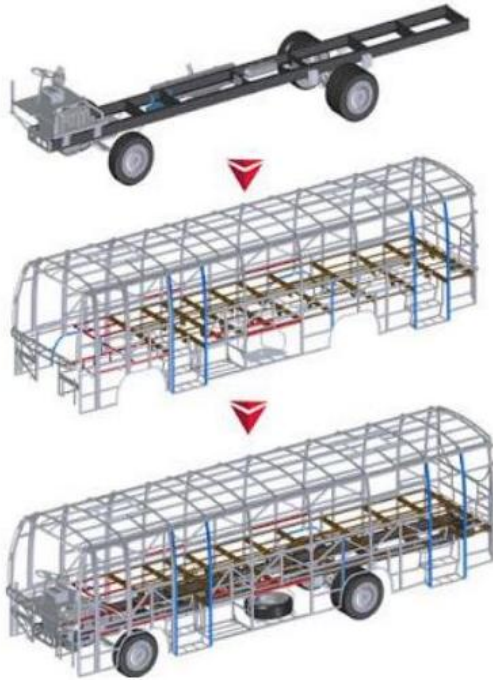
Mirror adjustment: Properly adjusted side and rearview mirrors are crucial for monitoring blind spots

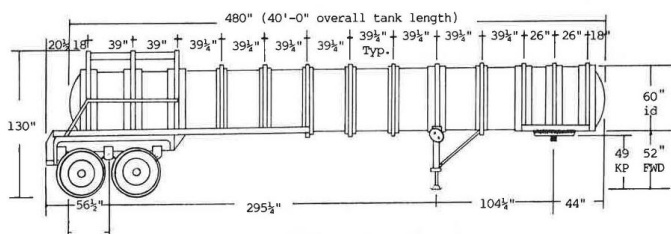
Bus design: The design of the bus, including the size and placement of windows, can affect the driver's field of view

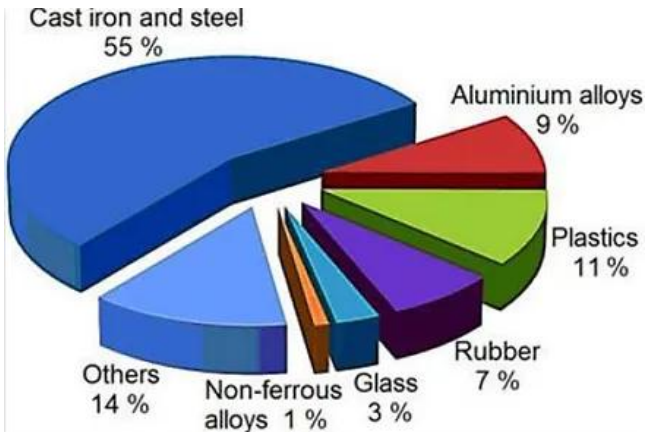
(Source: ARAI)

2.	a. Visibility tests conducted in certified labs. b. Photometry: Measurement of light from headlamps to check for adequate lighting. Both high and low beams are tested. c. Camera fixed at driver’s head location in the front seat. i. A complete 360° sweep indicates how much is visible through windshields and side windows. ii. Obstruction by A, B, and C pillars, roof, headrests, antennas, wipers, and other attachments is assessed.	1	10	1	3	T
----	---	---	----	---	---	---

	iii. LOS for down viewing tested to see if low objects on the road can be detected. iv. Detected views in side and rearview mirrors, swept area of windshields, headlamp beam pattern/length/coverage area checked. v. The H-point (torso and thigh joint at the hip) of the driver should be located. Optimized with the seat recline angle for clear LOS. 					
3.	Ladder frame chassis – conventional bus fabrication: 	2	10	2	3	T





	• Hemispherical ends; 48" crown radius • Designed to carry liquids and gases • Oval and cylindrical tank trailers reduce internal stress • High C.G; more prone to rollover • Liquid sloshing in partially filled tanks • Volume: 5500-11,600 gallons • Tanks have baffles and multiple compartments inside • Ideal for milk, gasoline, diesel, LPG, oils, etc.					
5.	Aluminum contributes to 9% of overall body materials:  Sheet aluminum contributes to 30-60% weight reduction. • Ductile, malleable, tensile, recyclable • Lighter than steel, same strength • Rust resistant • Corrosion resistant (but not as good as SS) • Special welding and machining needed • Bends under loads easily • More expensive than steel. Energy intensive extraction • Alloys: Cold rolled Al-Si, Al-Mg, Al-Mn, Al-Si-Mg, Al-Zn-Mg alloys	4	10	2	4	T
6.	Flowfield around a car:	5	10	3	4	T

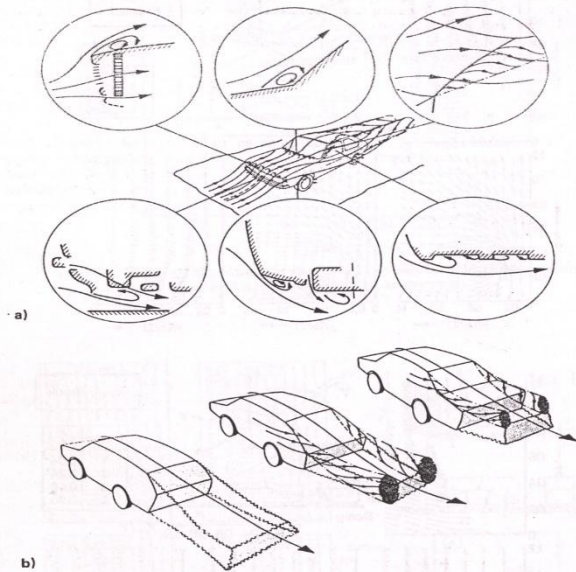


Fig. 4.3 Airflow around a car and the main flow separations: a) on the front-end structure, b) on the three types of car back.

Impact of drag on tractive force:

$$F_T - R - mg \sin \theta - D = m \frac{dV}{dt}$$

Total fuel consumption for power driving (overcoming drag):

$$B[L/100km] = C \frac{\frac{1}{\rho_{fuel}} \int_{F_T > 0} \left[-sfc \frac{P_{b,T}}{F_T} dt + sfc P_{b,A} \right] + \int_{F_T < 0} \dot{b}_b dt + \int_{F_T = 0} \dot{b}_{acc} dt}{\int_0^t V dt}$$

7.

Rear diffuser:

A rear diffuser is a device that shapes the airflow under the rear of the car.

It creates a low-pressure zone behind the car, which reduces drag and lift

Smoother underbody:

A smooth underbody reduces drag by smoothing the passage of air under the car.

Fit a full smooth under tray, including covering the exhaust.

Reduce the size of tire wakes

Suck turbulent air inboard

Eject turbulent air up and over the car behind

Increase the width of the tires

5

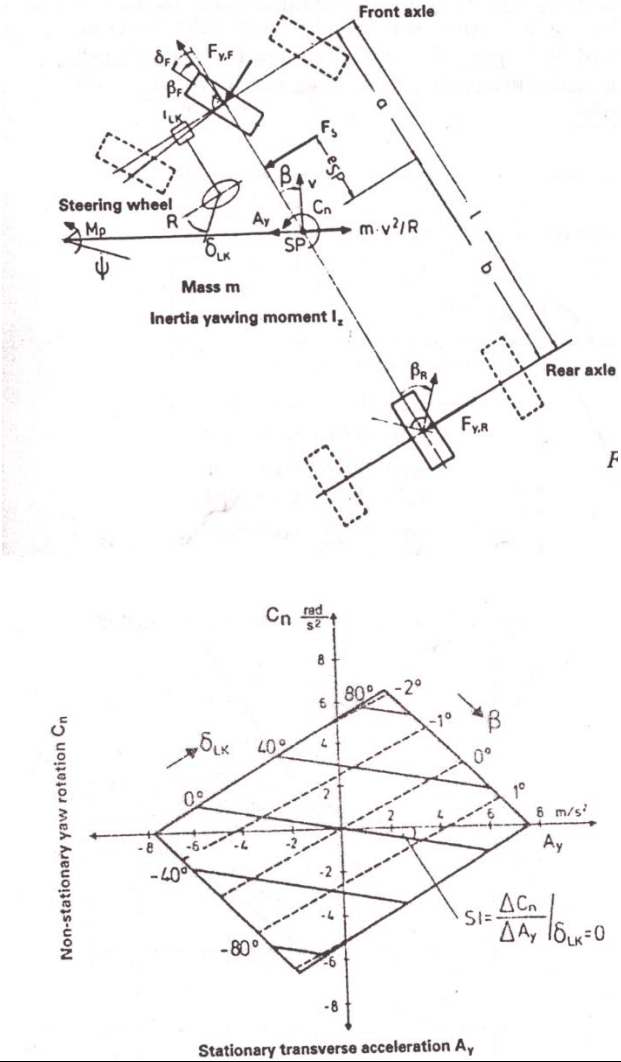
10

3

4

T

8.	a. Monopole : A monopole source models the intensity of sound as being proportional to the fourth power of the velocity. $I \sim V^4$. Monopoles are produced due to transient or oscillating flows. Ex : Oscillating flow in the engine intake and exhaust ducts. If a exterior pressure fluctuation on the vehicle causes an interior volumetric air pocket from the vehicle to leak, that would constitute a secondary monopole. b. Dipole : Dipoles are formed due to the interaction between exterior flows, and the chassis. Ex : A fluctuating pressure on the car surface can produce a dipole type noise which will be $\sim V^6$. c. Quadrupoles : Quadrupoles are produced by the interaction between two fluid elements. The intensity of sound produced by such sources is weak, and is $\sim V^8$. Since $I_{\text{quadrupole}}/I_{\text{dipole}} \sim M^2$, quadrupoles can be neglected in comparison to dipoles, which are always present. To measure wind noise on a car using microphones, one typically mount specialized microphones on the exterior of the vehicle, often in strategic locations like the door mirrors or windshield frame, to capture the air pressure fluctuations caused by wind while the car is moving, allowing analysis of the noise spectrum and identification of areas where wind noise is most prominent; this process usually involves using specialized microphones with windshields and employing data analysis techniques to isolate the wind noise from other vehicle sounds. A high-quality microphone with a suitable preamplifier is needed to capture the sound accurately. The microphone is strategically placed within the car cabin, often near the driver's ear position, to best represent the perceived noise level. On-road testing: Driving at various speeds on a controlled road to assess real-world wind noise.	6	10	4	5	T

	• • Wind tunnel testing: Considered the most accurate method, as it allows for controlled wind conditions and isolation from other noise sources. Sound pressure level (dB): The measured wind noise is typically expressed in decibels (dB). • • Frequency spectrum: Analyzing the frequency components of the noise can help identify specific sources of wind noise. (Source: Swamy Mukkera, Senthilkumar Raamya Premkumar, Deshpande Samar, Prasath R, "A Test Methodology for Vehicle Wind Noise Reduction and Acoustic Quality Improvement", SAE International, article no.: 2019-26-0216).					
9.	A)  The diagram illustrates vehicle dynamics with forces $F_{y,F}$, $F_{y,R}$, F_z, and moments M_p, I_x. It also shows steering wheel angle δ_{LK}, yaw angle β, and yaw rate $\dot{\beta}$. The graph below shows the relationship between non-stationary yaw rotation C_n (rad/s²) and stationary transverse acceleration A_y (m/s²) for various steering angles δ_{LK} (0°, 20°, 40°, 60°, 80°). The slope $SI = \frac{\Delta C_n}{\Delta A_y} \big _{\delta_{LK}=0}$ is indicated.	6	10	4	5	T
		6	10	4	5	T

$$\dot{\psi} = I_F \cdot F_{SF} - I_R F_{SR} + e_{SP} \frac{Y}{I_Z}$$

$$A_Y = \frac{F_{SF} + F_{SR} + Y}{m}$$

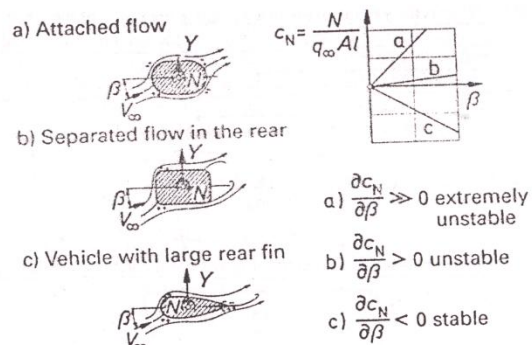
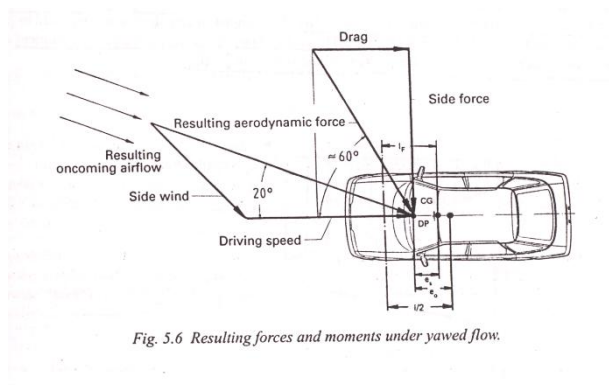
- For a straight driving, $\delta_{LK} = 0$, the SI is

$$\left. \frac{\Delta C_N}{\Delta A_Y} \right|_{\delta_{LK}=0}$$

- A higher negative stability index would yield more stability.
- Driving stability generally decreases for speeds more than 150 kmph (94 mph).
- Stability can however be improved by attaching flow spoilers like fins, or negative delta wings.
- Rear end additions reduce lift force on rear axle, but increase drag.
- However, if the side wind angle is less than the critical yaw angle, the increase in fuel consumption due to higher drag, is negligible.

(OR)

B)



10.	A) Fig. 14.4 Wheelbase and tread-width adjusting possibility using eccentric plates, after K.B. KELLY, et al. [14.3]. (OR) B) Fig. 14.5 Measurement of the frontal area by laser technology, after M.-A. BEECK and B. STOFFREGEN [14.4].	7	10	5	5	T
	↔↔↔↔					

↔↔↔↔

M.S. Yagnabalkar

March 6, 2025

Signature with date