



VIT

Vellore Institute of Technology

SCHOOL OF COMPUTER SCIENCE AND ENGINEERING
CONTINUOUS ASSESSMENT TEST - I
WINTER SEMESTER 2024-2025

REG.NO.:

SLOT: B1+TB1

Programme Name & Branch : B.Tech (CSE & Specializations)
Course Code and Course Name : BCSE311L and Sensors and Actuator Devices
Faculty Name(s) : Common for all
Class Number(s) : Common for all
Date of Examination : 28.01.2025
Exam Duration : 90 minutes
Maximum Marks: 50

General instruction(s):

- Answer All Questions
- M - Max mark; CO - Course Outcome; BL - Blooms Taxonomy Level (1 - Remember, 2 - Understand, 3 - Apply, 4 - Analyse, 5 - Evaluate, 6 - Create)
- CO1: Classify different Sensors & Actuators based on various physical phenomena and differentiate their performance characteristics.
- CO2: Analyze the working principles of thermal, optical & electric sensors and actuators to interpret their mathematical model.

Q. No	Question	M	CO	BL
1.	Investigate the following terms precisely based on given criteria:- > Vision > Touch Given Criteria: ★ What ★ Why ★ How ★ Where ★ When Based on your investigation, analyze whether the loss of vision or touch would create more challenges and issues. Provide enough justifications with real life scenarios. Note: - You should narrate complete investigation as well as suitable real-life sub-scenarios for vision & touch in your answer.	10	CO 1	B L 3
2.	Elucidate using a real life scenario how calibration and reliability plays a major role in choosing sensors for any critical application. A temperature sensor is calibrated using a reference temperature of 150°C. During the calibration, the sensor gives a reading of 154°C. The sensor has a measurement range of 0°C to 240°C with a specified accuracy of $\pm 2^\circ\text{C}$ and a drift rate of 0.6% per year and is cumulative every year. ✓ What is the calibration error in terms of percentage error relative to the reference temperature? ✓ Calculate the reliability of the sensor after 12 years, considering the drift rate. ✓ Compute the sensor's output if the actual temperature is 160°C for year 3, 6, 9, 12, 15. ✓ Plot a graph for year vs sensor output and state your observations. Suggest remedies to reduce calibration errors.	10	CO1	B L 2



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3.	Explain the effect of sensor non-linearity on the accuracy and reliability of measurements. How does non-linearity impact systems that require precise control, such as industrial automation or temperature monitoring? Discuss methods to compensate for non-linearity and improve sensor performance.	CO1 10	B L 2
4.	Provide a in-depth analysis with detailed explanation for the following sensors by applying the given terms:- - Optical thermo-mechanical Sensors - Acoustical thermo-mechanical Sensors Given terms: - Sensitivity and Accuracy - Speed of Response - Environmental Effects - Energy Efficiency - Application selectivity Design and develop a data acquisition system using your analysis as per the guidelines:- - Scenario – post earthquake - Need to schedule unmanned rescue cart - Highest priority for rescuing live people trapped inside the collapsed structures Note: - You must provide appropriate illustrations, sensors and actuator selection as well as relevant validations in your answer.	CO2 10	B L 3
5.	A spool of magnet wire (copper wire insulated with a thin layer of polyurethane) contains 400 m of wire with a diameter of 0.2 mm. It is proposed to use the spool as a temperature sensor to sense the temperature in a freezer. The proposed range is between- 50°C and +15° C. A milliammeter is used to display the temperature by connecting the sensor directly to a 1.2 V battery and measuring the current through it. [conductivity as $\sigma_0 = 5.8 \times 10^7$ S/m at 20 °C TCR of copper $\alpha = 0.0039$] - Calculate the resistance of the sensor and the corresponding currents at the minimum and maximum temperatures. - Calculate the maximum power the sensor dissipates. - Discuss various factors that influence the response time of a Resistance Temperature Detector (RTD).	CO2 10	B L 2