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**VIT**

Vellore Institute of Technology  
(Chartered to be University under section 3 of UGC Act, 1956)

SLOT: B2+TB2

REG. NO.:

**SCHOOL OF MECHANICAL ENGINEERING  
CONTINUOUS ASSESSMENT TEST (CAT) -II  
WINTER SEMESTER 2025-2026**

Program Name & Branch : B. Tech - BMA, BME, BMM  
Course Name Code : BMEE330L  
Course Name : Control Systems  
Faculty Name(s) : Prof. Chinmaya Sahu, Prof. Ashirbad Swain, Prof. Suresh Kumar  
Class Number(s) : VL2025260502985, 2499, 2988  
Date of Examination : 16-03-2026  
Maximum Marks: 50

Exam Duration: 90 mins

**General instruction(s):**

- Answer All Questions
- M - Max mark; CO - Course Outcome; BL - Blooms Taxonomy Level (1 - Remember, 2 - Understand, 3 - Apply, 4 - Analyse, 5 - Evaluate, 6 - Create)
- Course Outcomes Statements:  
CO. 2: Develop various representations of system based on the first principles approach  
CO. 3: Infer the domain specifications from the time and frequency response.  
CO. 4: Analyse the stability of closed-loop systems using different techniques

| Q. No | Question                                                                                                       | M  | CO | BL |
|-------|----------------------------------------------------------------------------------------------------------------|----|----|----|
| 1.    | Applying block diagram reduction technique to find the overall transfer function of the system shown in Fig. 1 | 10 | 2  | 3  |
|       | <p>Fig. 1</p>                                                                                                  |    |    |    |
| 2.    | Using Mason's rule find the overall gain of the system shown in Fig. 2                                         | 10 | 2  | 3  |
|       | <p>Fig. 2</p>                                                                                                  |    |    |    |

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3.

For a mass spring and damper system shown in Fig. 3 obtain the expression for displacement ( $x$ ) when a unit step force is applied as shown considering  $m = 1$  kg,  $k = 1$  N/m and  $b = 0.2$  Ns/m.

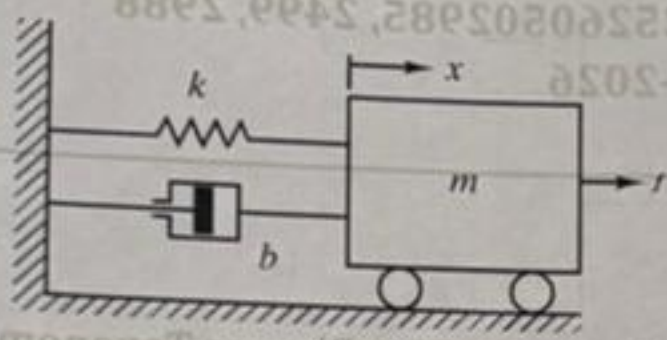


Fig. 3

Find, damped Natural frequency, % overshoot, settling time and steady state error for the system.

4.

The open-loop transfer function of a system is given as  $\frac{4}{s(s+3)}$ .

It is required to locate the poles of this transfer function at  $-7$  and  $-4 \pm 3j$  by using a PID controller. Calculate the values of controller gains so as to achieve the objective.

5.

Consider a unity feedback system with open loop transfer function  $\frac{4}{s(s^4+4s^3+8s^2+8s+7)}$ . Find the state of stability using Routh-Hurwitz criterion.

10

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3

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