

| Course Code | Course Title | L | T | P | C |
|---|--|--|---|-----------------------------|----------------|
| BCSE407L | Computer Vision | 3 | 0 | 0 | 3 |
| Pre-requisite | NIL | Syllabus version | | | |
| | | 1.0 | | | |
| Course Objectives | | | | | |
| <ol style="list-style-type: none"> 1. To solve real world problems with image or video as input. 2. To make use of low level image processing algorithms to provide information about the scene. 3. To emphasize on computer vision applications | | | | | |
| Course Outcomes | | | | | |
| At the end of the course the student will be able to | | | | | |
| <ol style="list-style-type: none"> 1. Analyze image formation using digital camera and its principles 2. Evaluate feature extraction and feature estimation for image or video 3. Apply 3D vision techniques 4. Identify the computer vision applications | | | | | |
| Module:1 | | Low Level Vision | | | 6 hours |
| Image Formation – Sampling and Aliasing – Linear Filters and Convolution – Correlation and Patterns – Image Pyramid | | | | | |
| Module:2 | | Feature Detection and Matching | | | 5 hours |
| Points and patches-Feature detectors, Feature descriptors, Feature matching, Feature tracking; Edges: Edge detection and linking; Vanishing points | | | | | |
| Module:3 | | Segmentation | | | 7 hours |
| Active Contours – Split and Merge – Mean Shift and Mode Shift – Normalized cut – Graph cut and Energy based methods – Deep Learning based Segmentation Models for Computer Vision | | | | | |
| Module:4 | | Motion Estimation and Recognition | | | 7 hours |
| Translational alignment – Parametric Motion - Spline-based motion – Optical Flow – Layered Motion- Object Detection – Face Recognition – Scene Understanding | | | | | |
| Module:5 | | Stereo Correspondence and 3D Reconstruction | | | 6 hours |
| Epipolar Geometry – Local Methods – Multi view stereo – Shape from X – Active Range finding – Model based reconstruction | | | | | |
| Module:6 | | Image Stitching and Image Rendering | | | 6 hours |
| Stitching: Motion models, Global alignment, Compositing; Rendering: Layered depth images, Light fields and Lumi graphs, Environment Mattes | | | | | |
| Module:7 | | Computer Vision Applications | | | 6 hours |
| Contour tracking and rotoscoping – Medical Image Segmentation – Video summarization and compression – Stereo based head tracking – Z-keying and background replacement | | | | | |
| Module:8 | | Recent Trends | | | 2 hours |
| Guest lectures from Industry and, Research and Development Organizations | | | | | |
| | | | | Total Lecture hours: | |
| | | | | 45 hours | |
| Text Book(s) | | | | | |
| 1. | Richard Szeliski, Computer Vision: Algorithms and Applications, Springer-Verlag London Limited, 2011 | | | | |
| Reference Books | | | | | |

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| 1. | Richard Hartley and Andrew Zisserman, Multiple View Geometry in Computer Vision, Second Edition, Cambridge University Press, March 2004. | | |
| 2. | Marco Alexander Treiber, Optimization for Computer Vision: An Introduction to Core Concepts and Methods, Springer 2013 | | |
| 3. | Alan C. Bovik, Handbook of Image and Video Processing, ISBN- 978-0123885623, ELSEVIER, ACADEMIC PRESS, 2005 | | |
| 4. | K. Fukunaga; Introduction to Statistical Pattern Recognition, Second Edition, Academic Press, Morgan Kaufmann, 1990. | | |
| 5 | R.C. Gonzalez and R.E. Woods, Digital Image Processing, Addison- Wesley, 1992 | | |
| Mode of Evaluation: CAT, written assignment , Quiz, FAT | | | |
| Recommended by Board of Studies | | 12-05-2023 | |
| Approved by Academic Council | | No. 70 | Date 24-06-2023 |